

Ch. 10 Vector Quantization

Overview

Motivation

Recall in Lossless Methods:

- Block Huffman is better than single-symbol Huffman
 - Blocks allow to exploit correlation between symbols (assuming source symbols are not independent!)
- Shannon proved that “blocking taken to the limit” achieves optimal compression... exploits correlation

Recall in Scalar Quantization:

- It is the lossy version of a single-symbol method
- Shannon also proved that for lossy we can achieve the theoretical bound on compression (R-D curve) via “blocking taken to the limit”

This blocking idea motivates Vector Quantization

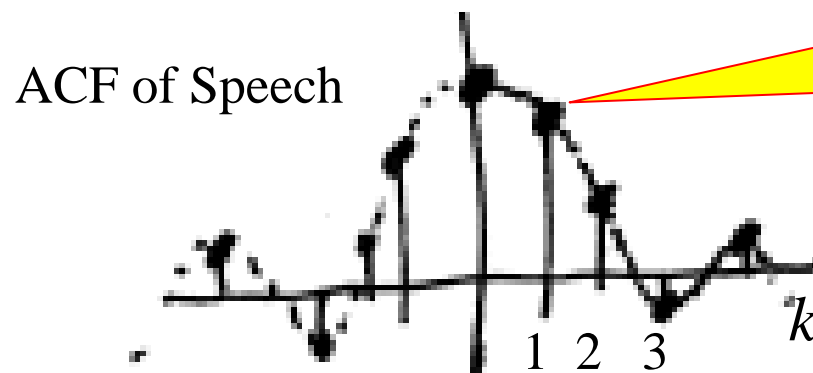
Main Idea of VQ

That info theory says to consider “blocking” to exploit correlation

→ Group into vectors (non-overlapping) and “quantize” each vector

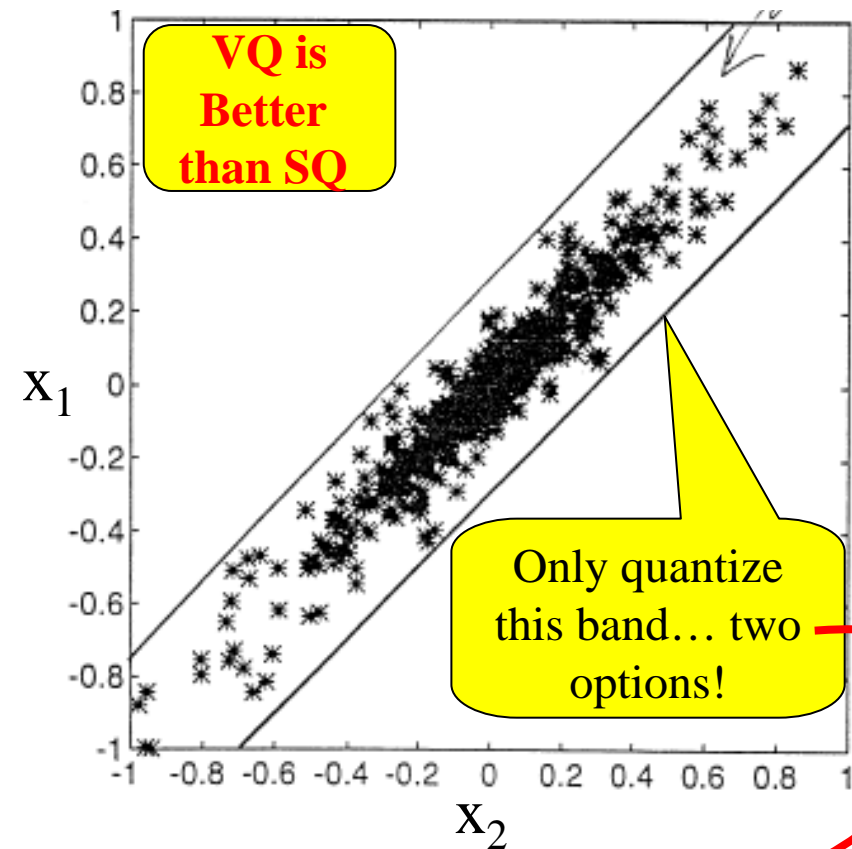
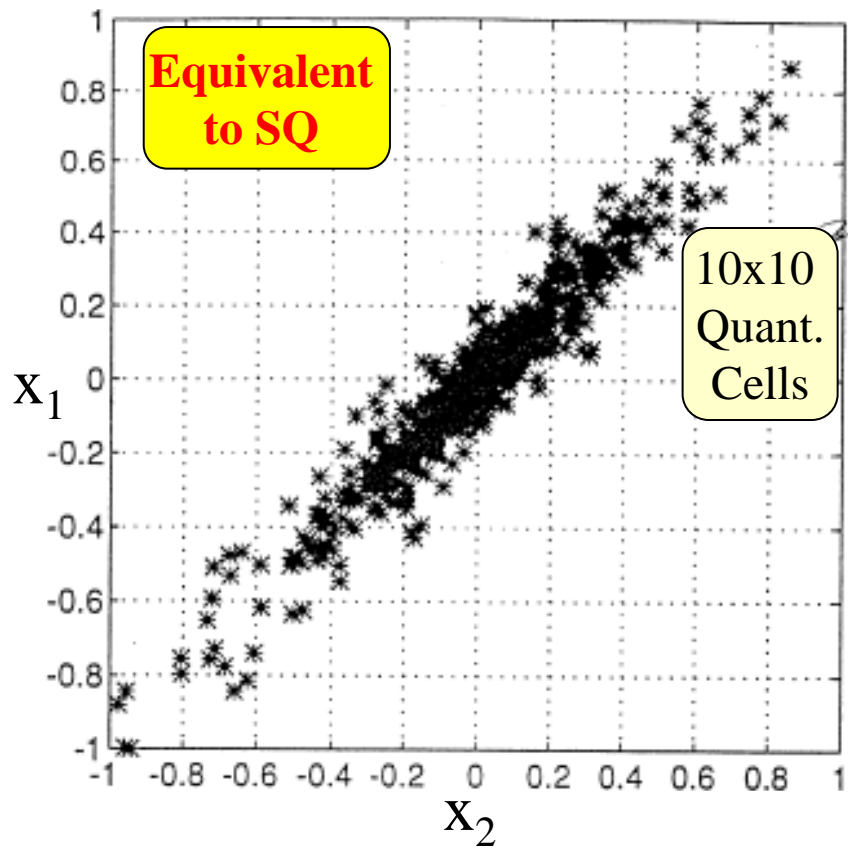


No Need to Limit to 2-D Vectors



Samples in vector are highly correlated!

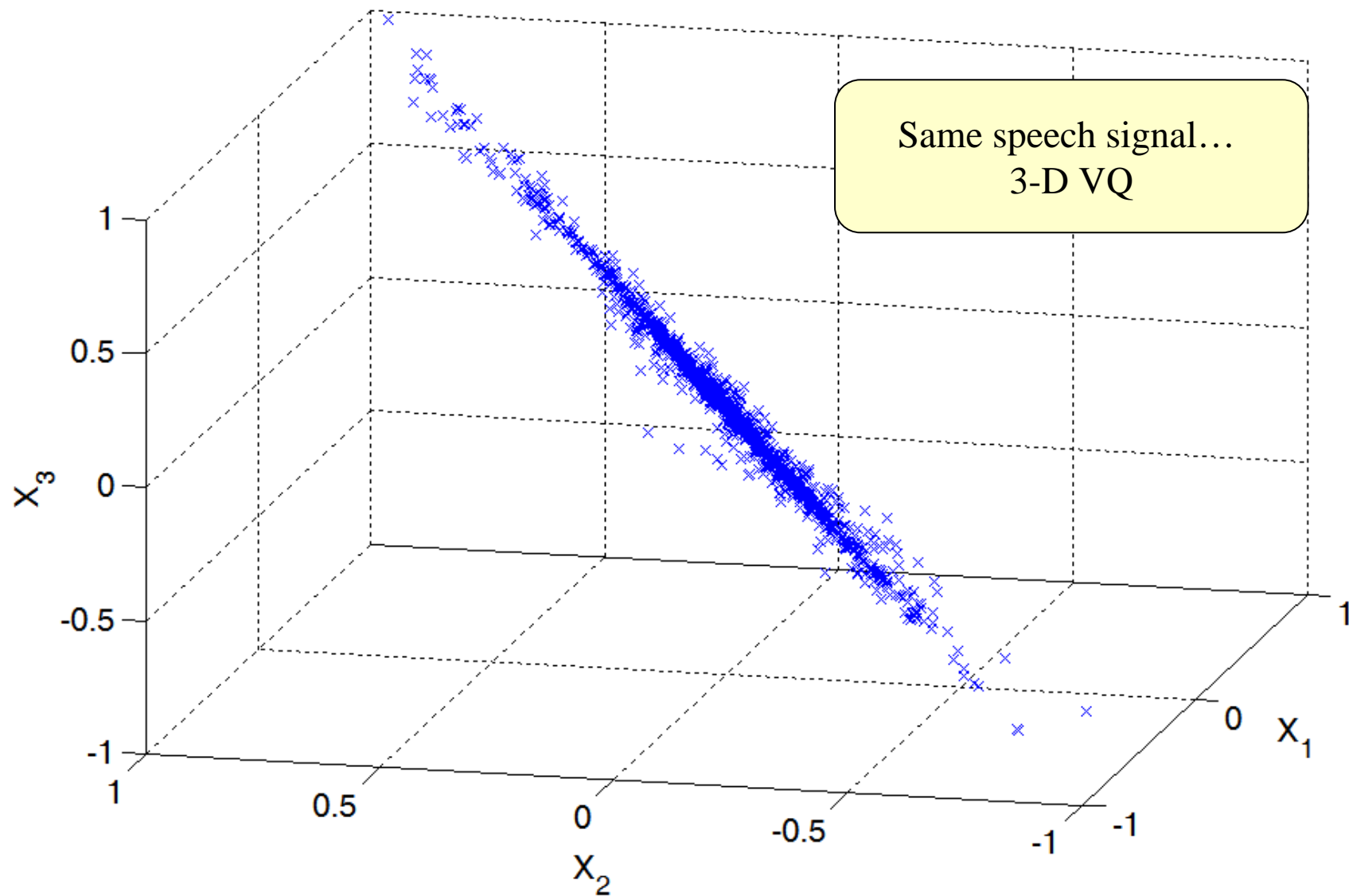
Illustration of Gain from VQ: Real Speech Data



- 100 cells smaller than SQ
 - Same Rate, Lower Distortion
- Fewer than 100 cells of same size as SQ
 - Lower rate, Same Distortion

Going to higher dimension: vectors concentrated in smaller
% of whole space → Improved Performance

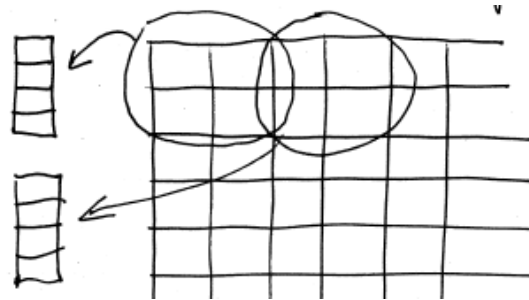
Scatter plot for 3-Dimensional vectors



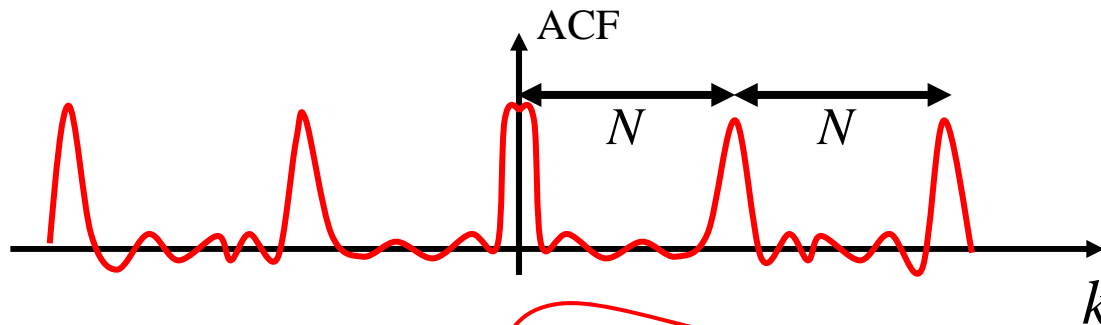
Forming Vectors

For time signals... we usually form vectors from temporally-sequential samples.

For images... we usually form vectors from spatially-sequential samples.

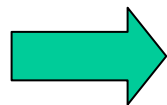


But... you should let the ACF structure guide your choice...



Note: Book uses upper-case italic to indicate a vector... I use the more standard lower-case bold non-italic...

$$\mathbf{x}_1 = [x[0] \quad x[N] \quad x[2N] \quad x[3N]]$$



$$\mathbf{x}_2 = [x[1] \quad x[N+1] \quad x[2N+1] \quad x[3N+1]]$$

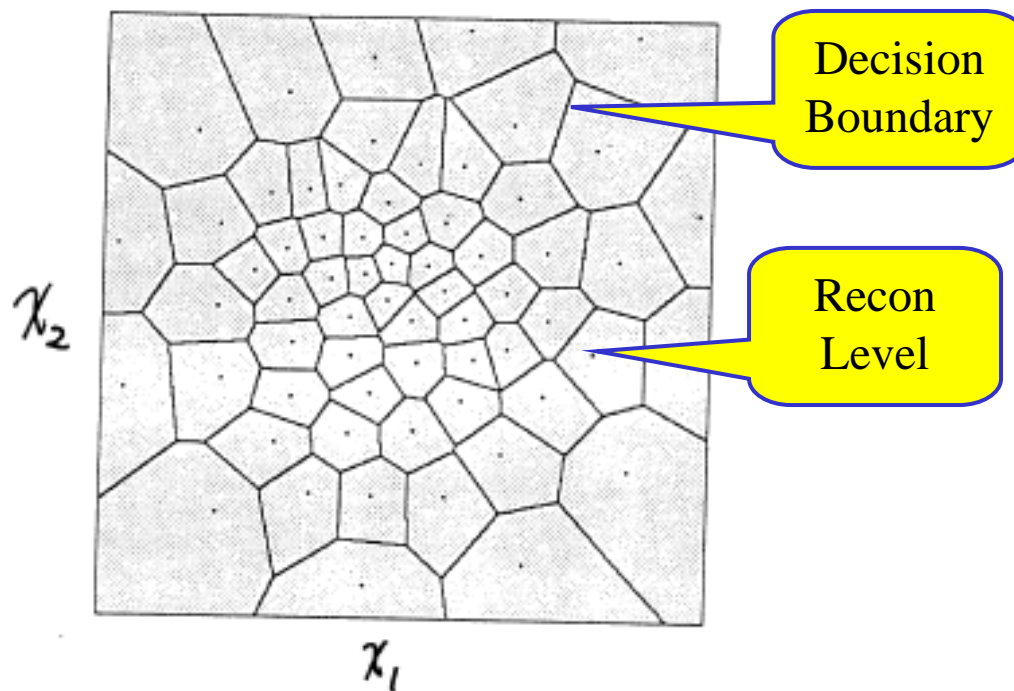
$$\mathbf{x}_3 = [x[2] \quad x[N+2] \quad x[2N+2] \quad x[3N+2]]$$

Designing VQ

Q: What does it mean to design a VQ?

A: Similar to SQ... Specify Decision Boundaries and Reconstruction Values... except now those are in N -D space... Goal is to minimize MSQE for a given rate (or vice versa)

Example of a VQ Design: For 2-D vectors taken from a sequence of independent Gaussian samples...



Somehow we need to design the DBs and RLs...

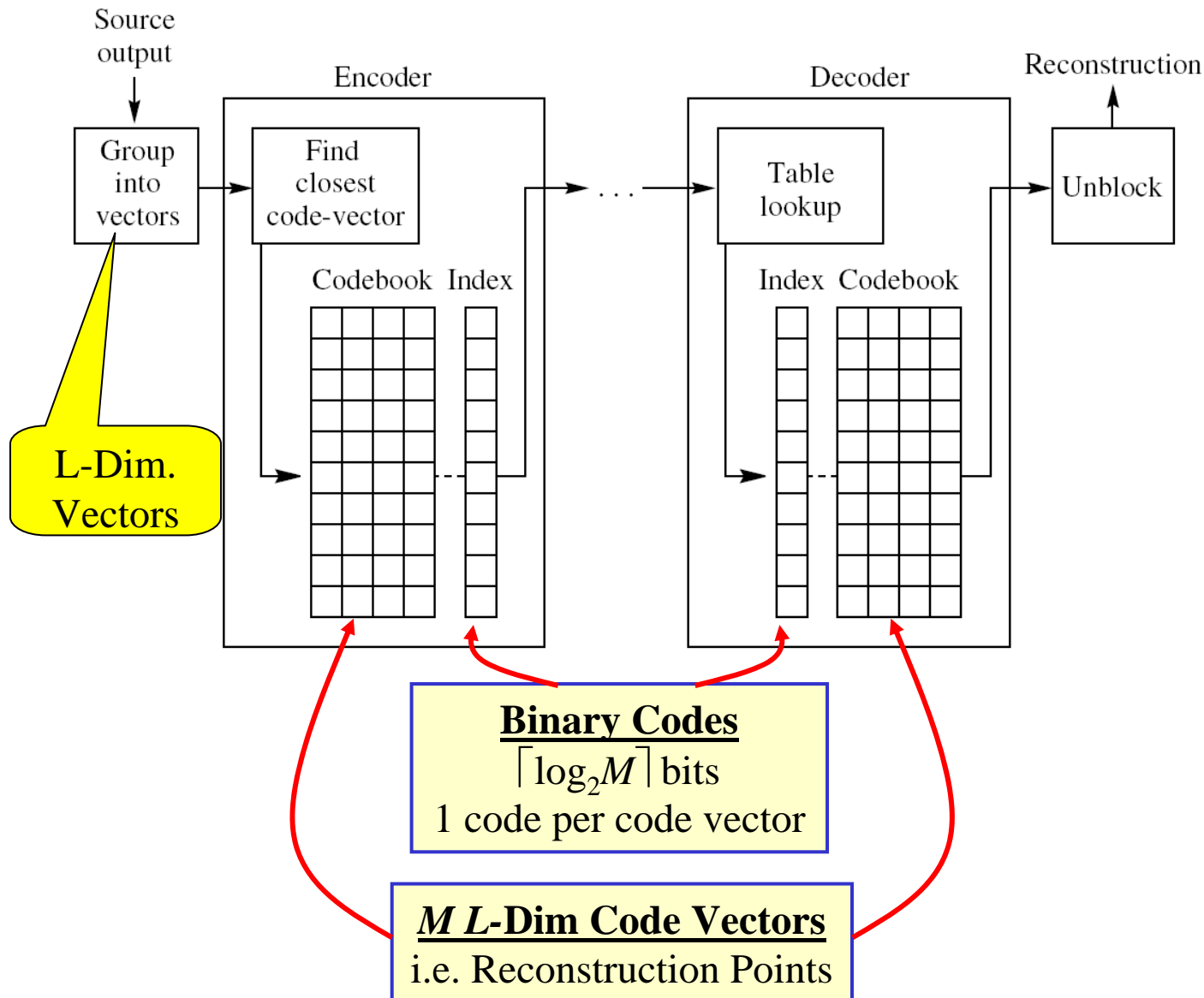
However, we really only need to specify the RLs...

Then the i^{th} Decision Region consists of all points closer to the i^{th} RL than they are to any other RL

We'll see how to do this later...

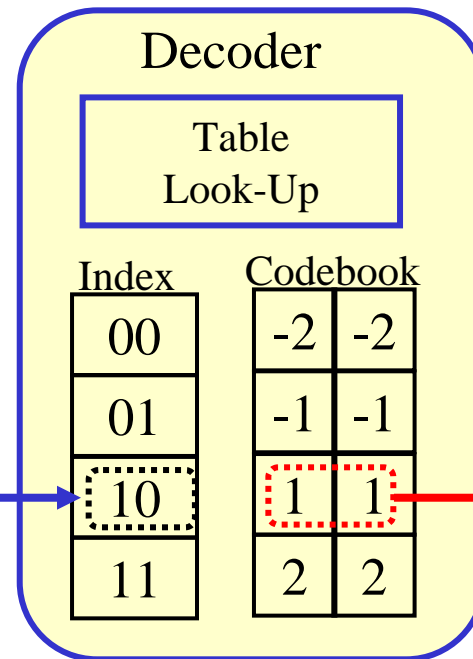
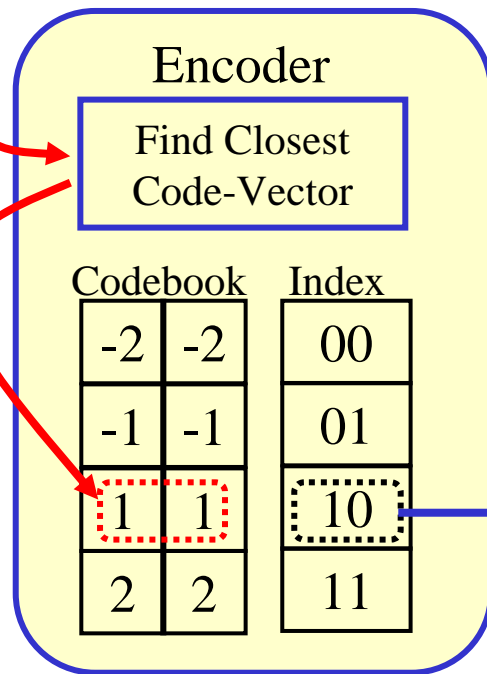
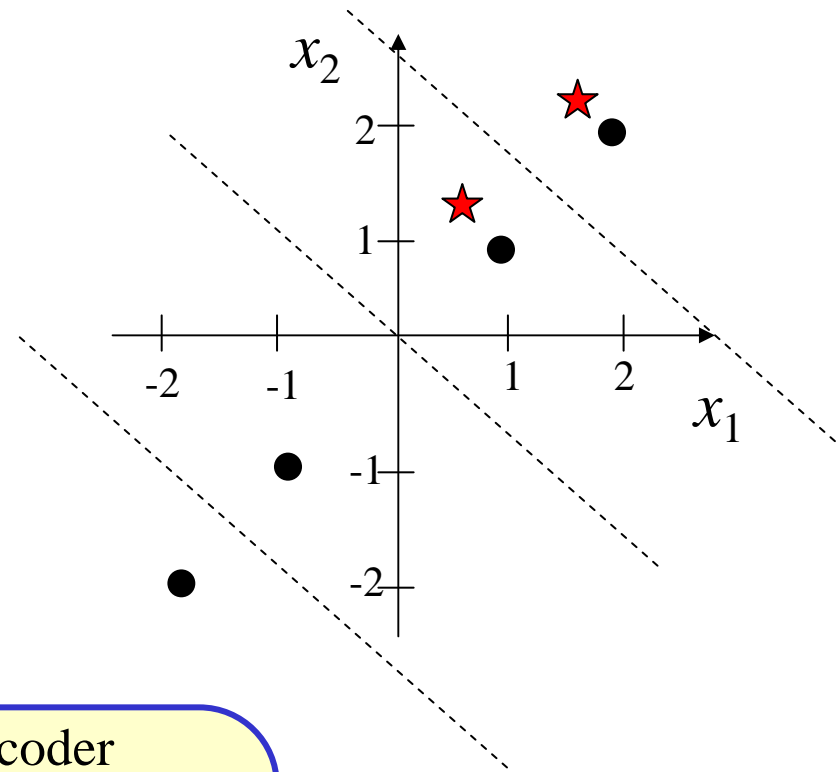
Structure of a VQ

Fig. 10.1 in Textbook



Example

$x[n]: \dots 0.75 \ 1.27 \ 1.78 \ 2.11 \dots$



Encoder & Decoder Operation

Encoder: *Search* codebook for code vector \mathbf{y}_j that is closest to input vector \mathbf{x} .

$$\text{Codebook } \{\mathbf{y}_i\}_{i=1}^M = C \quad \text{where each } \mathbf{y}_i \in \mathfrak{R}^L$$

\mathbf{x} is closest to \mathbf{y}_j if:

$$\|\mathbf{x} - \mathbf{y}_j\| \leq \|\mathbf{x} - \mathbf{y}_i\| \quad \forall \mathbf{y}_i \in C$$



$$d(\mathbf{x}, \mathbf{y}_j) \leq d(\mathbf{x}, \mathbf{y}_i) \quad \forall \mathbf{y}_i \in C$$

where $\|\mathbf{z}\| = \sqrt{\sum_{i=1}^L z_i^2}$ (Euclidian Norm)

for $\mathbf{z} = [z_1 \quad z_2 \quad \cdots \quad z_L]^T$

Notation: If \mathbf{x} is closest to \mathbf{y}_j we write $Q(\mathbf{x}) = \mathbf{y}_j$

Note: VQ cells are defined by the RLs & these equations rather than explicit boundaries!!!

Decoder: Use received binary codeword (the “index”) as an address into the codebook (i.e., Table Look-Up)

Complexity of VQ

Encoder is Computationally Complex

Must check all M y_i for closeness... must compute M norms

M can be quite large: 256, 512, 1024, etc.

Decoder is Easy & Fast

VQ Complexity is Asymmetrical

- May not work well for Real-Time Encoding
- But Real-Time Decoding is very easy

VQ Rate & Performance vs. Rate

If L -D vectors are quantized using a VQ having M reconstruction points we need binary codewords having

codeword length = $\lceil \log_2 M \rceil$ bits/vector

bits/sample = $\frac{\lceil \log_2 M \rceil}{L}$ bits/sample

“Typical” L values:

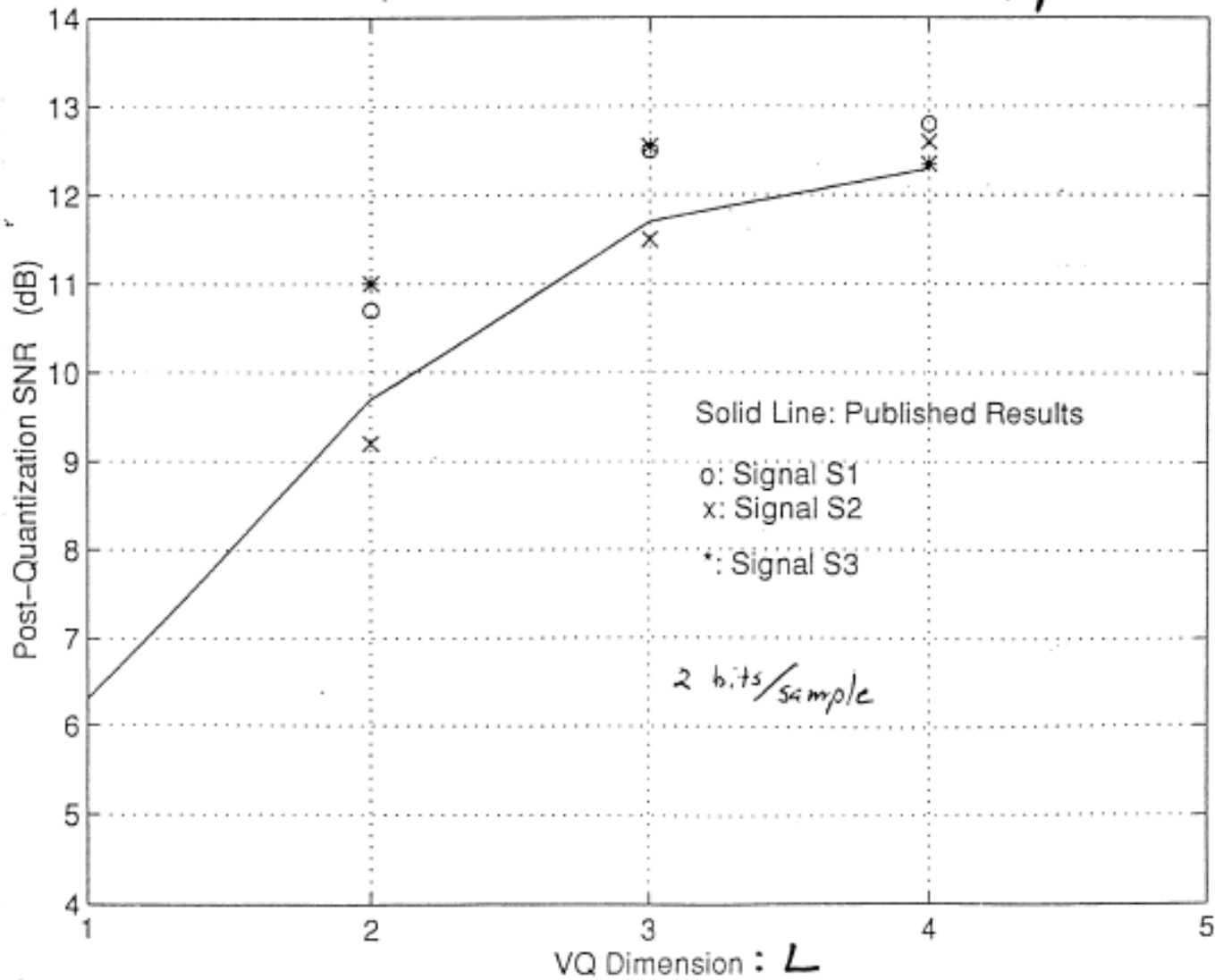
- Images: $L = 16$ (4x4)
- Speech: $L = 3,4,5,6$

Info Theory Says: Increasing L improves the VQ performance

Practice Says: ... only up to a point!

- Improvement decreases w/ increasing L
- Design gets harder w/ increasing L
- Encoder complexity grows w/ increasing L

Comparison of VQ Results with Published Results (Speech)



$L=5$
Design
was
not
achieved

2 bits/sample