

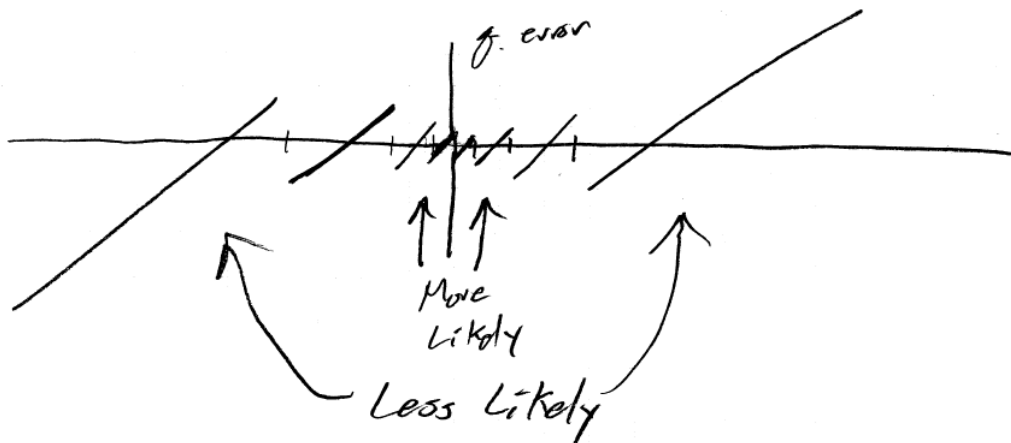
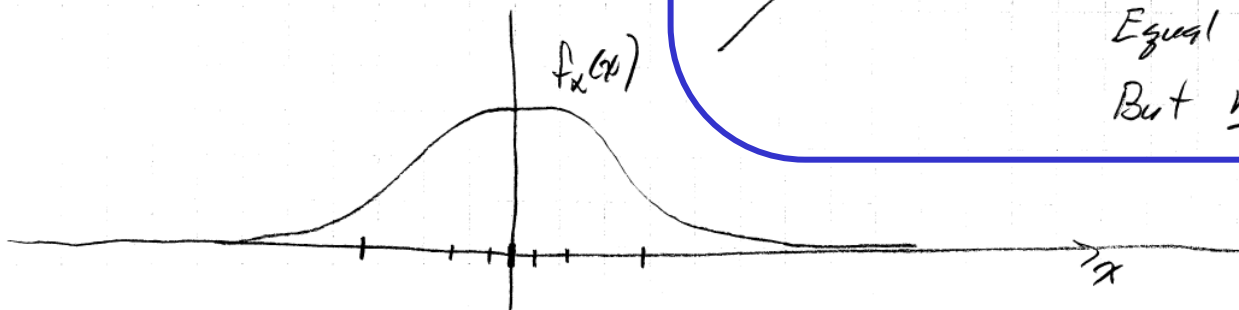
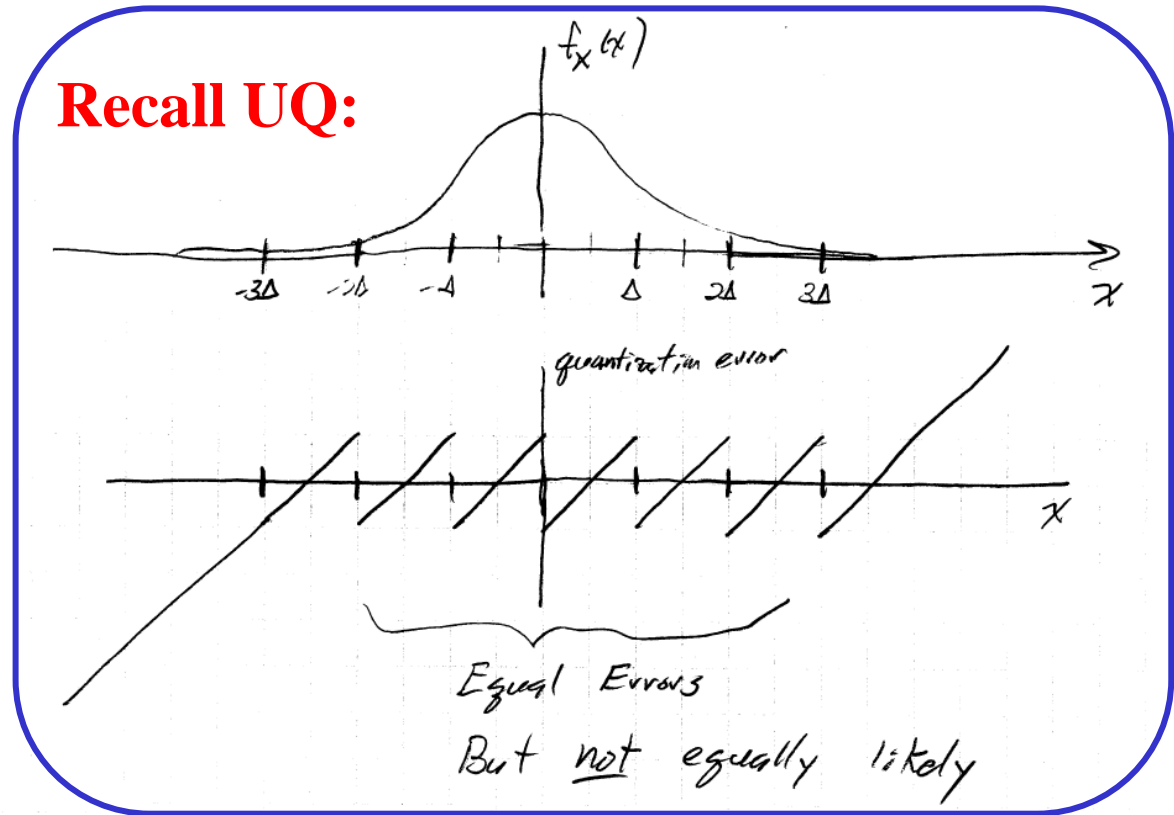
Ch. 9 Scalar Quantization

Non-Uniform Quantizers

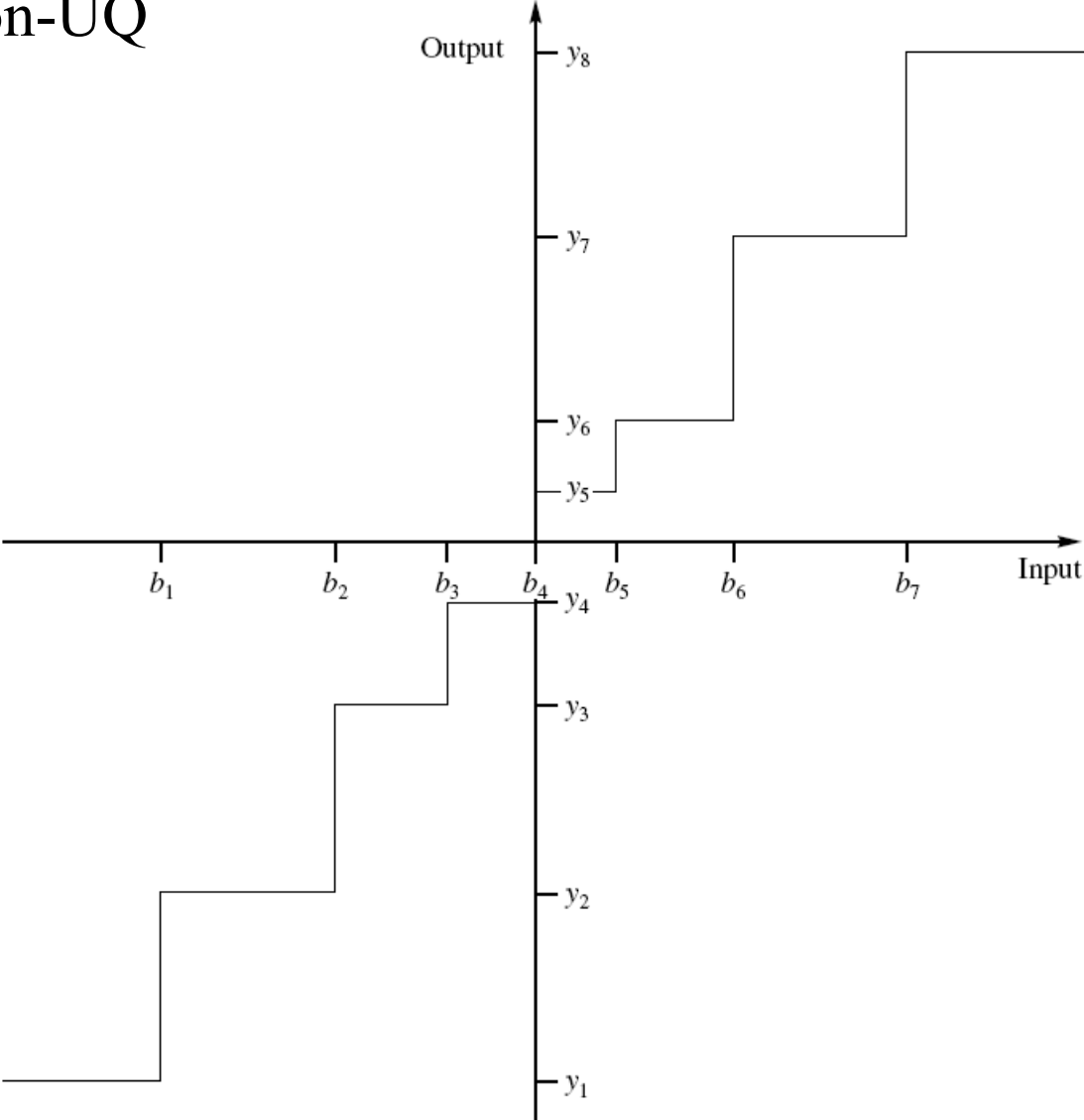
Motivation

Instead of doing this...

We'd like to make the errors small in the regions where the signal is most likely



Mid-Riser Non-UQ



Lloyd-Max Quantizer

Optimize only
w.r.t. one variable!

Recall for UQ optimization: $\min_{\Delta} \sigma_q^2(\Delta)$

Now more complex! Need to optimize w.r.t.

DBs: $b_1, b_2, b_3, \dots, b_{M-1}$
RLs: $y_1, y_2, y_3, \dots, y_M$

minimize $\sigma_q^2(b_1, b_2, \dots, b_{M-1}, y_1, y_2, \dots, y_M) = \sum_{i=1}^M \int_{b_{i-1}}^{b_i} (x - y_i)^2 f_X(x) dx$

First... set $\frac{d\sigma_q^2}{dy_j} = 0$

Note: only one term in this sum
remains after the derivative...

Solve for y_j to get:

$$y_j = \frac{\int_{b_{j-1}}^{b_j} x f_X(x) dx}{\int_{b_{j-1}}^{b_j} f_X(x) dx}$$

Centroid of PDF
in the interval

Next... set $\frac{d\sigma_q^2}{db_j} = 0$

$$b_j = \frac{y_{j+1} + y_j}{2}$$

Midpoint between
RLs

<Recall for UQ it was the other way around... RLs were midpoints of DLs>

Leads to two coupled equations... solved iteratively and numerically to give the “Lloyd-Max Quantizer” <See book for details on the algorithm>

$$y_j = \frac{\int_{b_{j-1}}^{b_j} x f_X(x) dx}{\int_{b_{j-1}}^{b_j} f_X(x) dx} \quad b_j = \frac{y_{j+1} + y_j}{2}$$

TABLE 9.6 Quantizer boundary and reconstruction levels for nonuniform Gaussian and Laplacian quantizers.

Levels	Gaussian			Laplacian		
	b_i	y_i	SNR	b_i	y_i	SNR
4	0.0	0.4528	9.3 dB	0.0	0.4196	7.54 dB
	0.9816	1.510		1.1269	1.8340	
6	0.0	0.3177	12.41 dB	0.0	0.2998	10.51 dB
	0.6589	1.0		0.7195	1.1393	
	1.447	1.894		1.8464	2.5535	
8	0.0	0.2451	14.62 dB	0.0	0.2334	12.64 dB
	0.7560	0.6812		0.5332	0.8330	
	1.050	1.3440		1.2527	1.6725	
	1.748	2.1520		2.3796	3.0867	

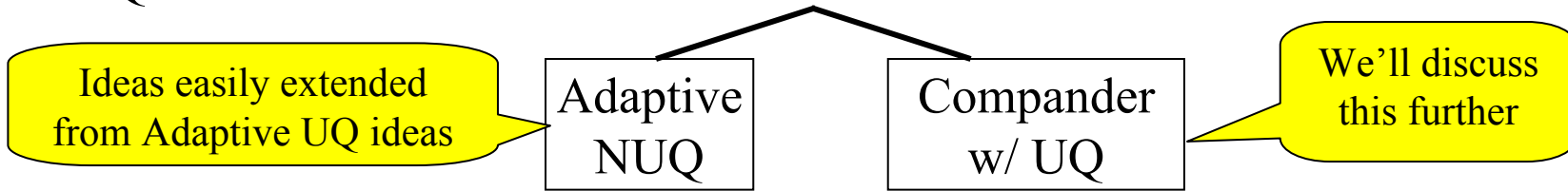
8-Level PDF-Opt. UQ:

14.27 dB

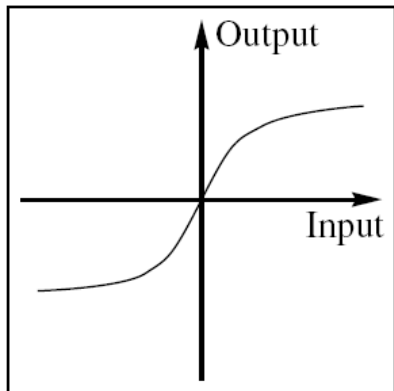
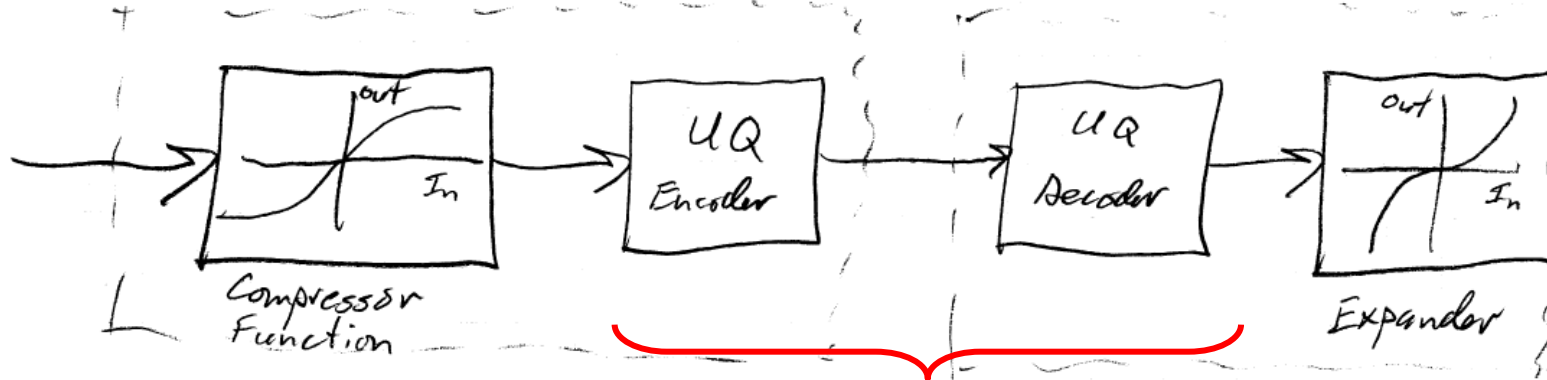
11.39 dB

Compeded Quantization - Overview

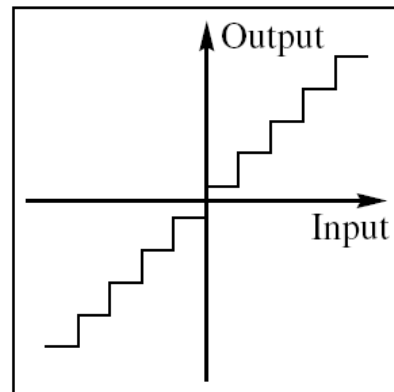
NUQs also suffer PDF Mismatch...



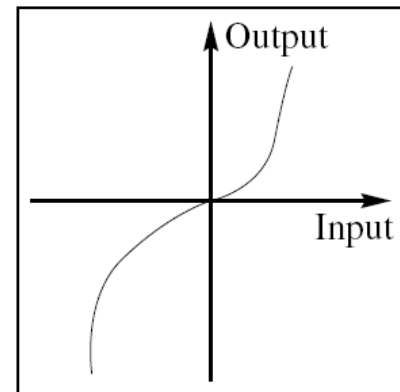
Comping:



Compressor



Uniform quantizer



Expander

Companded Quantization - Derivation

Goal: Choose compressor function $C(x)$ to give robust performance

Bound the input range: $|x| \leq x_{\max}$

Assume M-Level UQ

If rate of UQ is high enough...

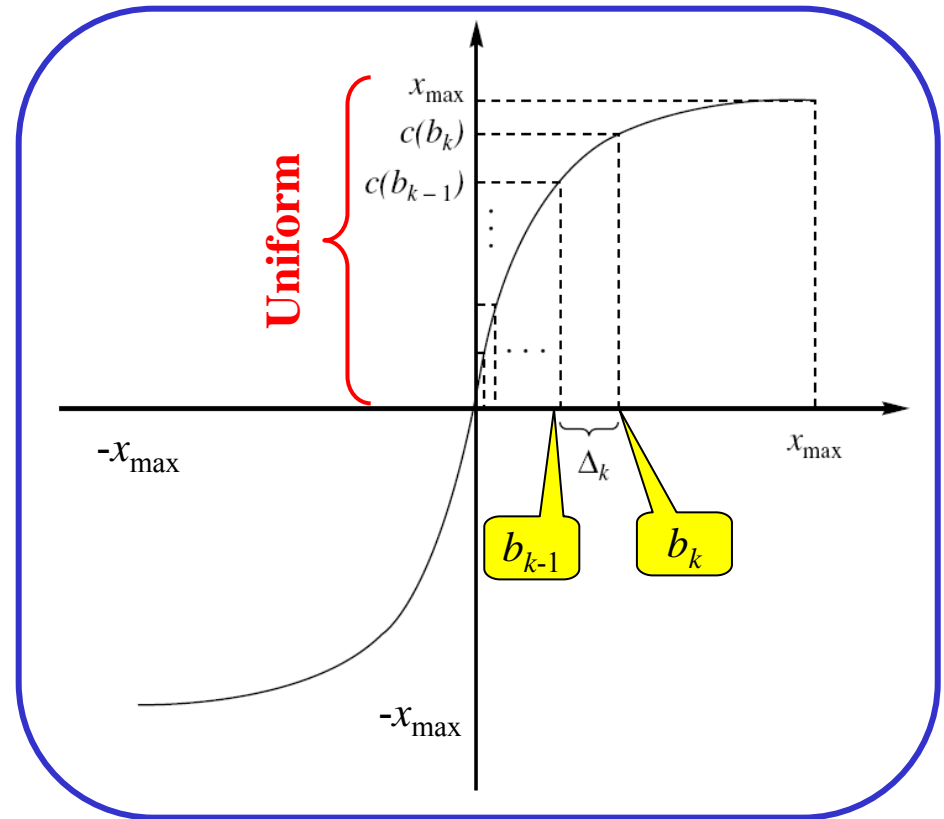
$$\left. \frac{dC(x)}{dx} \right|_{x=y_k} \approx \frac{C(b_k) - C(b_{k-1})}{\Delta_k}$$

$C'(y_k)$

$$= \frac{2x_{\max}/M}{\Delta_k}$$

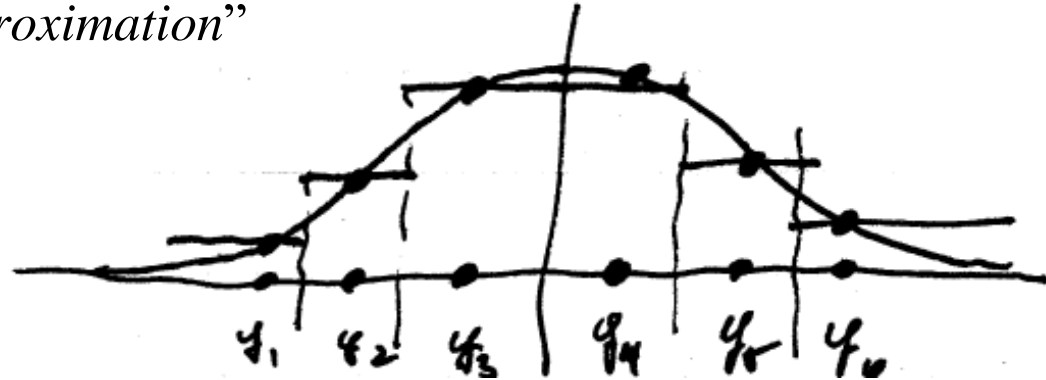
Solve for Δ_k :

$$\Delta_k = \frac{2x_{\max}}{MC'(y_k)} \quad (\star)$$



Now look at MSQE:
$$\sigma_q^2 = \sum_{i=1}^M \int_{b_{i-1}}^{b_i} (x - y_i)^2 f_X(x) dx$$

Approximate PDF with step-wise function... this is accurate if M is large enough: “High-Rate Approximation”



$$\sigma_q^2 \approx \sum_{i=1}^M f_X(y_i) \underbrace{\int_{b_{i-1}}^{b_i} (x - y_i)^2 dx}_{=\Delta_i \sigma_{UQ}^2(\Delta_i) = \Delta_i^3 / 12} = \frac{1}{12} \sum_{i=1}^M f_X(y_i) \Delta_i^3$$

Known from (★)

$$= \frac{1}{12} \sum_{i=1}^M f_X(y_i) \left(\frac{2x_{\max}}{MC'(y_k)} \right)^2 \Delta_i = \frac{x_{\max}^2}{3M^2} \sum_{i=1}^M \underbrace{\frac{f_X(y_i)}{[C'(y_k)]^2}}_{\text{Approx. as integral}} \Delta_i$$

Leave one here for integral differential

Approx. as integral

The result is...

$$\sigma_q^2 \approx \frac{x_{\max}^2}{3M^2} \int_{-x_{\max}}^{x_{\max}} \frac{f_X(x)}{[C'(x)]^2} dx$$

“The Bennett Integral”

Can we choose $C(x)$ to make this variance independent of the shape of $f_X(x)$???

Can we make the SQR entirely independent of $f_X(x)$????

Let's see what happens if we choose $C'(x)$ such that

α is a constant

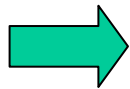
$$C'(x) = \frac{x_{\max}}{\alpha|x|}$$

Slope of $C(x)$

- is always positive
- $\rightarrow 0$ as $|x| \rightarrow \infty$
- $\rightarrow \infty$ @ $x=0$

Then...

$$\sigma_q^2 \approx \frac{\alpha^2}{3M^2} \underbrace{\int_{-x_{\max}}^{x_{\max}} x^2 f_X(x) dx}_{=\sigma_x^2} \Rightarrow MSQE \sim \sigma_x^2$$



$$SQR = \frac{\sigma_x^2}{\sigma_q^2} \approx \frac{3M^2}{\alpha^2}$$

Choosing $C(x)$ this way makes SQR constant regardless of PDF type and variance!!!

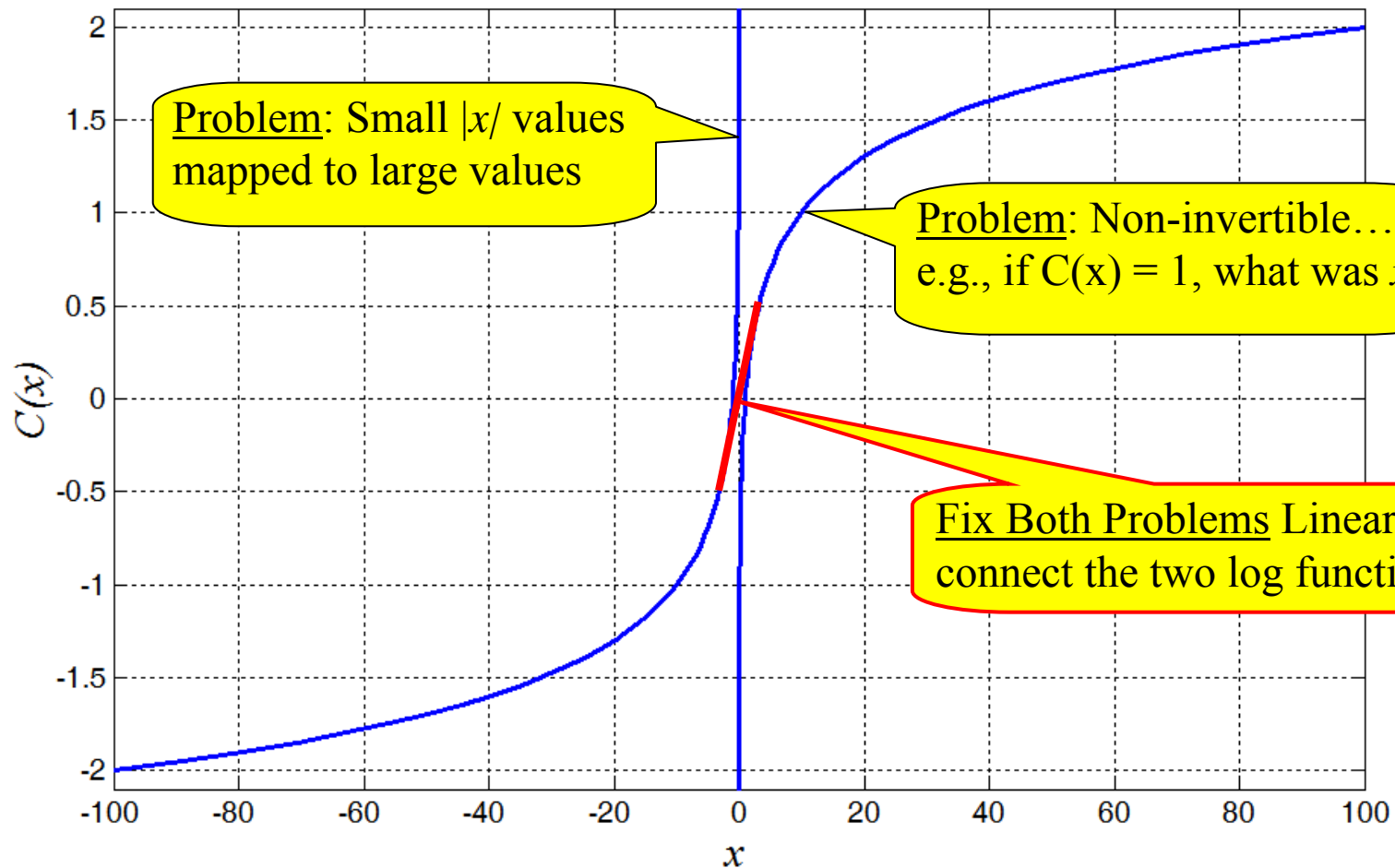
Can we actually find such a $C(x)$??

The form for function $C(x)$ that has the correct derivative is

$$C(x) = A + \frac{x_{\max}}{\alpha} \operatorname{sgn}(x) \ln(|x|)$$

Eq. (9.52) in 3rd Ed.
Text (and (8.52) in 2nd
Ed.) is not quite correct..

<A is a constant we can choose as $A = 0$ >

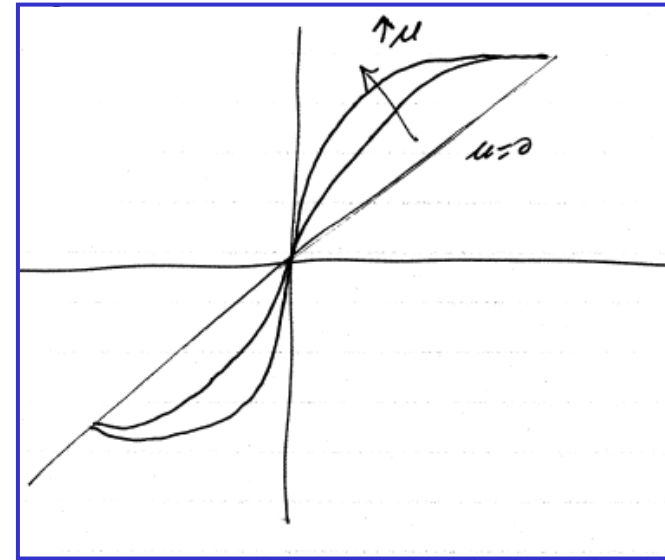


There are two common functions used to enact this approximation:

μ-Law (used in N. America & Japan phone systems)

$$C(x) = x_{\max} \frac{\ln\left(1 + \mu \frac{|x|}{x_{\max}}\right)}{\ln(1 + \mu)} \operatorname{sgn}(x)$$

$\mu = 255$ is the standard



• **A-Law** (used in phone systems elsewhere)

$$C(x) = \begin{cases} \frac{A|x|}{\ln(1+A)} \operatorname{sgn}(x), & 0 \leq \frac{|x|}{x_{\max}} \leq \frac{1}{A} \\ x_{\max} \frac{1 + \ln\left(\frac{A|x|}{x_{\max}}\right)}{\ln(1+A)} \operatorname{sgn}(x), & \frac{1}{A} \leq \frac{|x|}{x_{\max}} \leq 1 \end{cases}$$

What SQR does μ -Law give? To answer, use μ -Law function in Bennett Integral:

$$SQR = \frac{3M^2}{[\ln(1 + \mu)]^2} \frac{1}{1 + \frac{2|\bar{\tilde{x}}|}{\mu\sigma_{\tilde{x}}^2} + \frac{1}{\mu^2\sigma_{\tilde{x}}^2}}$$

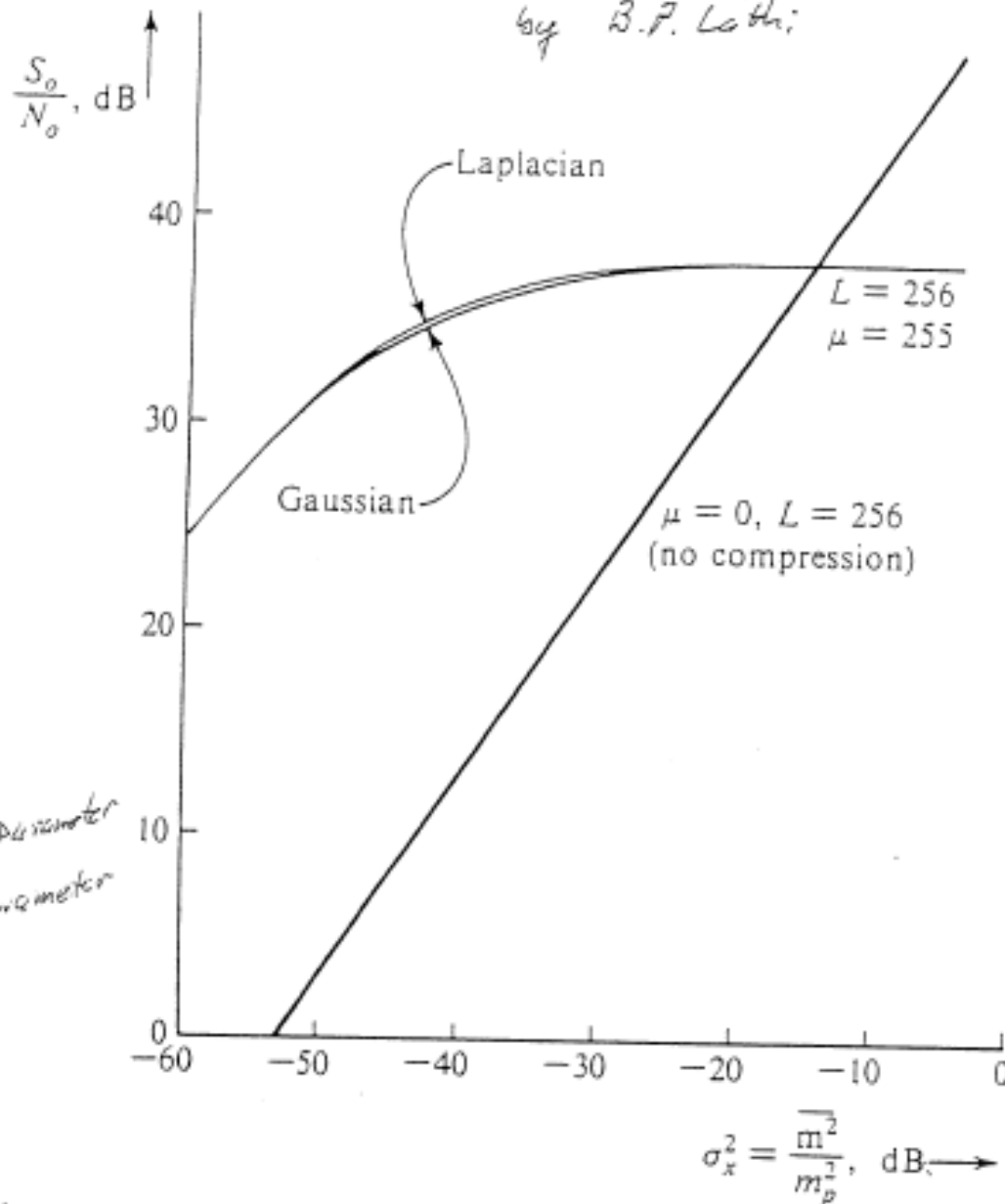
$$\tilde{x} = \frac{x}{x_{\max}} \quad |\bar{\tilde{x}}| = E\{|\tilde{x}|\}$$

For large μ : $SQR \approx \frac{3M^2}{[\ln(1 + \mu)]^2}$ **Constant!**

Note the Trade-Off:

- Large μ improves robustness by de-emphasizing these terms
- But... large μ reduces the SQR level that is achieved

From: Modern Digital and Analog Comm. Syst.
by B.P. Lathi



Note
 m_p is system parameter
 Not signal parameter

Figure 6.17 PCM performance with and without companding.

From: Digital Comm: Fund. and Appl. by B. Sklar

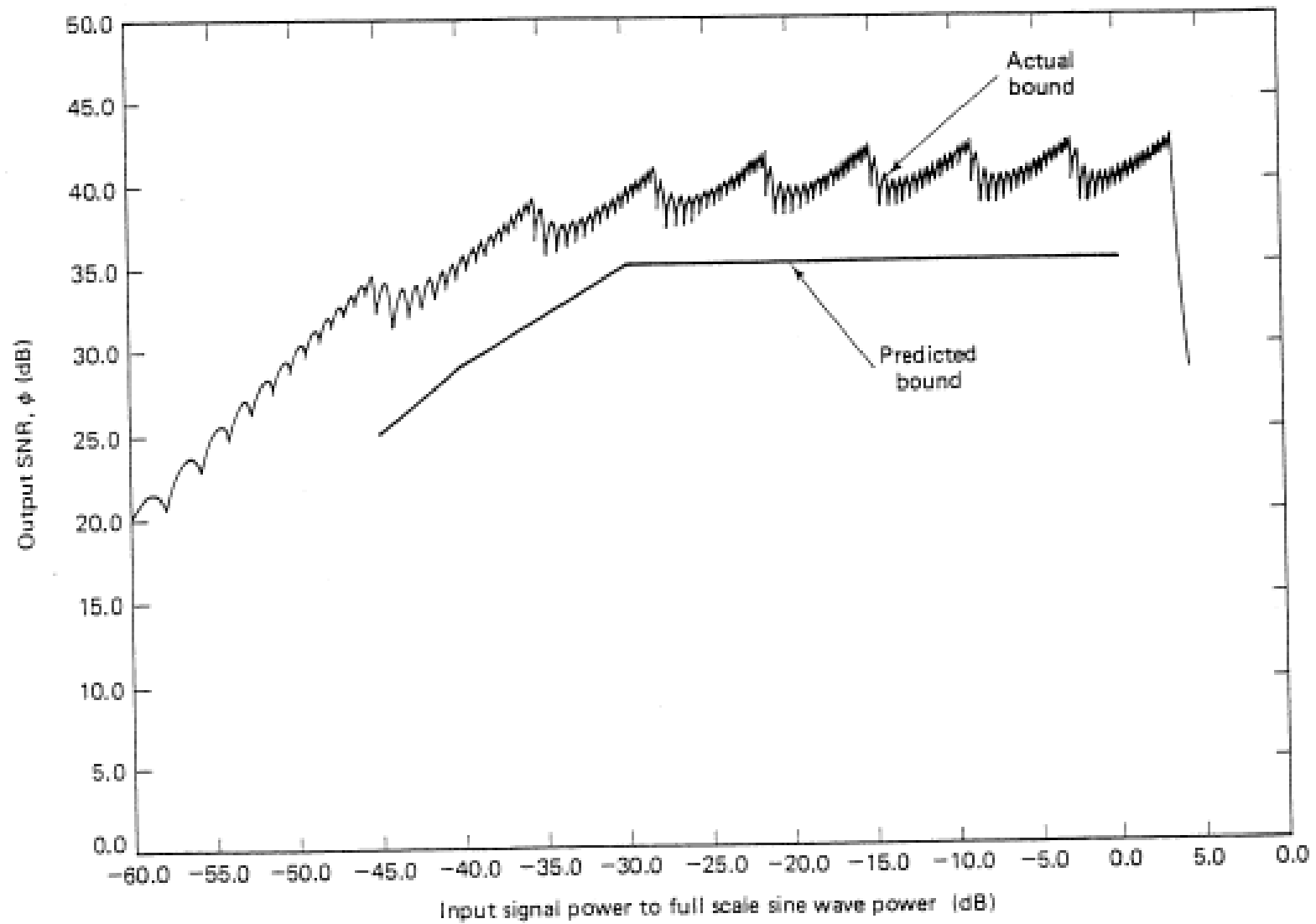


Figure 11.15 Predicted and measured SNR for a μ -law quantizer.